



$$v_i = RC \frac{dv}{dt} + v$$

$$\frac{dv}{dt} + \frac{1}{RC} v = \frac{V_m}{RC} \cos(\omega t)$$

Now just math

$$e^{\int \frac{1}{RC} dt} = e^{t/RC}$$

Find integrating factor

$$e^{t/RC} \frac{dv}{dt} + \frac{1}{RC} v e^{t/RC} = e^{t/RC} \frac{V_m}{RC} \cos(\omega t)$$

$$\int \frac{d}{dt} \left[e^{t/RC} v \right] = \int e^{t/RC} \frac{V_m}{RC} \cos(\omega t)$$

$$e^{t/RC} v = \frac{V_m}{\tau} \int e^{t/\tau} \cos(\omega t)$$

$$e^{t/\tau} v = \frac{V_m}{\tau} \left[\frac{e^{t/\tau} \omega \sin(\omega t) + \frac{e^{t/\tau}}{\tau} \cos(\omega t)}{\frac{1}{\tau^2} + \omega^2} \right] + K_1$$

$$v = K_1 e^{-t/\tau} + \frac{V_m}{\tau(\frac{1}{\tau^2} + \omega^2)} e^{t/\tau}$$

$$Y = A \cos \omega t + B \sin \omega t = Y = \sqrt{A^2 + B^2} \cos(\omega t + \tan^{-1}(\frac{B}{A}))$$

$$\left. \begin{array}{l} A = \frac{e^{t/\tau}}{\tau} \\ B = e^{t/\tau} \omega \\ \tan^{-1} \left[- \frac{\frac{e^{t/\tau} \omega}{\tau}}{\frac{e^{t/\tau}}{\tau}} \right] \\ \tan^{-1}(-\tau \omega) \end{array} \right\} \begin{array}{l} \sqrt{\frac{e^{2t/\tau}}{\tau^2} + e^{2t/\tau} \omega^2} \cos(\omega t + \phi) \\ e^{t/\tau} \sqrt{\left(\frac{1}{\tau^2} + \omega^2\right)} \cos(\omega t + \phi) \end{array}$$

$$v = K_1 e^{-t/\tau} + \frac{V_m e^{t/\tau} \sqrt{\left(\frac{1}{\tau^2} + \omega^2\right)} \cos(\omega t + \phi)}{\tau(\frac{1}{\tau^2} + \omega^2)}$$

$$v = k_1 e^{-t/\tau} + \frac{V_m \cos(\omega t + \phi)}{\tau \sqrt{\frac{1}{\tau^2} + \omega^2}} \sqrt{1 + \omega^2 \tau^2}$$

$$v = k_1 e^{-t/\tau} + \frac{V_m \cos(\omega t + \phi)}{\tau \sqrt{\frac{1 + \omega^2 \tau^2}{\tau^2}}}$$

$$v = k_1 e^{-t/\tau} + \frac{V_m \cos(\omega t + \phi)}{\sqrt{1 + \omega^2 \tau^2}}$$

Transient + steady state

$$v_c = k_1 e^{-t/RC} + \frac{\cos(2\pi f t + \phi)}{\sqrt{1 + (2\pi f RC)^2}}$$

$$\phi = \tan^{-1}(-2\pi f RC)$$

Appendix:

why integrating factor works?

$$\frac{dy}{dx} + P(x)y = f(x)$$

$$e^{\int P(x) dx} \frac{dy}{dx} + e^{\int P(x) dx} P(x)y = f(x)$$

$$\frac{d}{dx} \left(e^{\int P(x) dx} y \right) \quad \checkmark \text{ check}$$